

# Contents

<b>Key nomenclature</b> .....	7
<b>Preface</b> .....	9
<b>1. Damping in mechanical systems</b> .....	11
1.1. Reasons of damping .....	11
1.2. Dissipative forces in discrete systems .....	12
1.3. General damping model and damping model uncertainty .....	16
1.4. Dissipative forces in continuous systems .....	18
1.5. Optimal damping .....	22
1.6. Physical criteria of dampers' classification .....	24
<b>2. Magnetorheological dampers</b> .....	26
2.1. Magnetorheological fluids .....	26
2.2. Principles of magnetorheological dampers .....	29
2.3. Shock absorber for suspended seat applications .....	34
2.4. Friction damper for experimental use .....	36
2.5. The response time of magnetorheological dampers .....	38
<b>3. Control concepts</b> .....	43
3.1. Feedback model-based or model-less approaches .....	43
3.2. Finite time linear-quadratic regulator .....	45
3.3. Simple on-off condition depended controllers .....	49
3.4. Rule-based controllers .....	50
3.5. Neural adapted on-line control .....	52
3.6. Fuzzy control .....	53
<b>4. Real-time control – fundamentals</b> .....	56
4.1. Real-time operation mode .....	56
4.2. Real-time operating system .....	57
4.2.1. Task management. Scheduling and task management .....	59
4.2.2. Task synchronization and inter-task communication .....	60
4.2.3. Access to the measurement and control I/O channels .....	64
4.3. MS-Windows and real-time operating mode .....	64
4.3.1. Native MS-Windows timer services .....	64
4.3.2. Real-Time Windows Target .....	66
4.3.3. xPC target .....	67

4.4. FPGA-based system-on-a-chip real-time operating mode .....	68
4.4.1. Architecture of FPGA circuits.....	68
4.4.2. System-on-a-chip.....	69
4.4.3. Xilinx Xilkernel .....	70
<b>5. Measurement and control equipment .....</b>	<b>72</b>
5.1. Measurement-control system .....	72
5.2. Hardware .....	73
5.2.1. Sensors .....	73
5.2.2. Power controller.....	76
5.3. Signal conditioning .....	79
5.4. Signal conversion .....	81
5.4.1. Off-line processing .....	82
5.4.2. On-line processing .....	85
5.4.3. Signal filtering .....	86
<b>6. Control of a magnetorheological damper in a driver's seat suspension .....</b>	<b>89</b>
6.1. Model of the system .....	89
6.2. Algorithms .....	91
6.3. Experimental setup .....	93
6.4. Experiments .....	94
6.5. Microcontroller based control system .....	100
6.5.1. Microcontroller architecture and integrated development environment .....	100
6.5.2. Implementation of a selected algorithm and results.....	103
<b>7. Control of magnetorheological dampers in a vehicle suspension .....</b>	<b>108</b>
7.1. Model of the system .....	108
7.2. Algorithms .....	111
7.3. Experimental setup .....	116
7.4. Experiments .....	119
7.5. Microcontroller based control system.....	129
7.5.1. Microcontroller architecture and integrated development environment .....	129
7.5.2. Implementation of a selected algorithm and results.....	130
<b>8. Control of a magnetorheological damper attached to a cable .....</b>	<b>135</b>
8.1. Model of the system .....	135
8.2. Algorithms .....	136
8.3. Experimental setup .....	138
8.4. Experiments .....	140
8.5. FPGA based control system .....	152
8.5.1. FPGA architecture and integrated development environment .....	152
8.5.2. Implementation of a selected algorithm and results.....	153
<b>Summary .....</b>	<b>157</b>
<b>References .....</b>	<b>158</b>